

Notice of References Cited

Application/Control No.

10/596,048

Applicant(s)/Patent Under
Reexamination
TAKENAKA ET AL.

Examiner

MCDIEUNEL MARC

Art Unit

3664

Page 1 of 1

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	A	US-2006/0214622	09-2006	Summer et al.	318/568.12
*	B	US-7,339,340	03-2008	Summer et al.	318/568.12
*	C	US-4,662,465	05-1987	Stewart, David E. S.	180/8.1
*	D	US-7,120,518	10-2006	Takenaka et al.	700/245
*	E	US-2002/0022907	02-2002	TAKENAKA et al.	700/245
*	F	US-2007/0152620	07-2007	Takenaka et al.	318/568.13
	G	US-			
	H	US-			
	I	US-			
	J	US-			
	K	US-			
	L	US-			
	M	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)			
	U	Yang et al., Generation of optimal fault tolerant locomotion of the hexapod robot over rough terrain using evolutionary programming, 1997, IEEE, pg. 489-494			
	V	Netto et al., Fuzzy systems to solve inverse kinematics problem in robots control: application to an hexapod robots' leg, 2000, IEEE, pg. 150-155			
	W	Youcef et al., Control of the trajectory of a hexapod robot based on distributed Q-learning, 2004, IEEE, pg. 277-282			
	X				

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.